

Multi-Weighted Reachability Games

Thomas BRIHAYE¹ and Aline GOEMINNE²

1. UMONS – Université de Mons, Belgium.
2. F.R.S.-FNRS & UMONS – Université de Mons, Belgium.

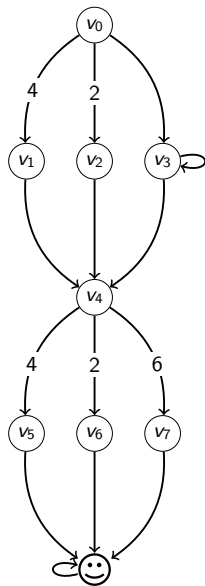
Highlights'23

1 Two-Player Multi-Weighted Reachability Games

2 Studied problems

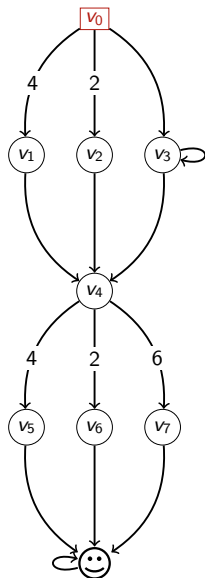
3 Conclusion

Reachability Games



Is it possible to reach 😊 with cost $\leq c$?

Reachability Games

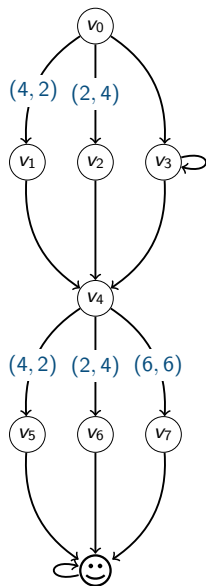


Is it possible to reach ☺ with cost $\leq c$?



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whatever the behavior of
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Reachability Games



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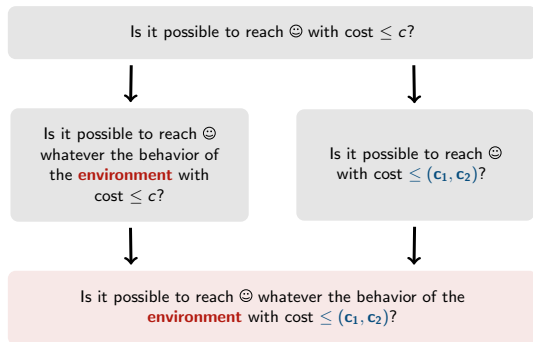
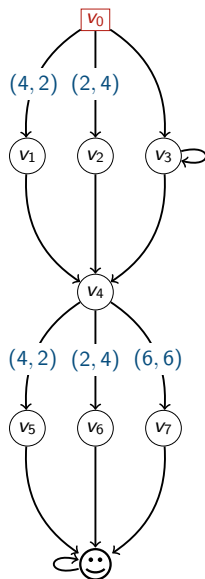


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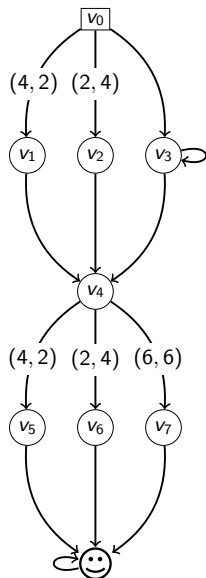
Is it possible to reach ☺
with cost $\leq (c_1, c_2)$?

Reachability Games



Two-Player Multi-Weighted Reachability Games

Two-Player Multi-Weighted Reachability Games



- A d -weighted graph $G = (V, E, (w_i)_{1 \leq i \leq d})$
- Two players: Player \circ and Player \square ;
- Turn-based;

Quantitative reachability objective

Given a target set $F \subseteq V$, for all **plays** (infinite paths in G) $\rho = \rho_0 \rho_1 \dots$:

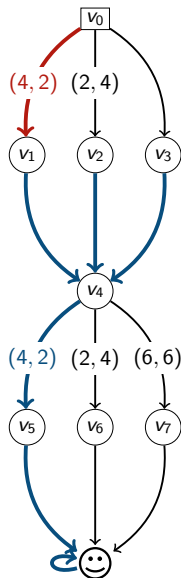
$$\text{Cost}_i(\rho) = \begin{cases} \sum_{n=0}^{k-1} w_i(\rho_n, \rho_{n+1}) & \text{if } k \text{ is the least} \\ & \text{index st. } \rho_k \in F \\ +\infty & \text{otherwise} \end{cases}$$

Rem: **same target set** for all dimensions.

Ex:

- $\text{Cost}(v_0 v_3^\omega) = (\text{Cost}_1(v_0 v_3^\omega), \text{Cost}_2(v_0 v_3^\omega)) = (+\infty, +\infty)$
- $\text{Cost}(v_0 v_1 v_4 v_5 (\text{smiley})^\omega) = (10, 6)$

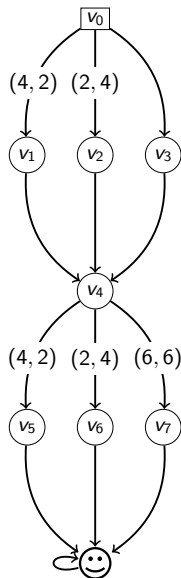
Two-Player Multi-Weighted Reachability Games



- A strategy for Player \bigcirc : $\sigma_{\bigcirc} : V^* V_{\bigcirc} \rightarrow V$.
- Given a **strategy profile** $(\sigma_{\bigcirc}, \sigma_{\square})$ and an initial vertex $v_0 \rightsquigarrow$ only one consistent play $\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{v_0}$ called the **outcome**.

Ex: $\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{v_0} = v_0 v_1 v_4 v_5 (\text{☺})^\omega$.

Two-Player Multi-Weighted Reachability Games



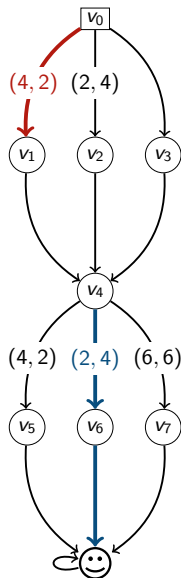
Player \bigcirc can **ensure** a cost profile $\mathbf{c} = (c_1, \dots, c_d)$ from v if **there exists** a strategy σ_{\bigcirc} such that **for all strategies** σ_{\square} of Player \square :

$$\text{Cost}(\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_v) \leq_{\mathbf{c}} \mathbf{c} = (c_1, \dots, c_d)$$

Ex:

- $(8, 8) \rightsquigarrow$ **Yes. (with memory!)**

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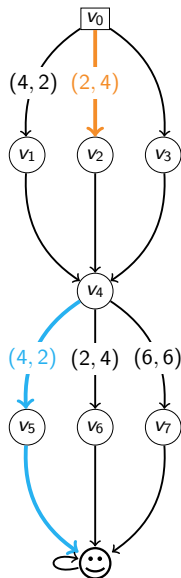
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■ \mapsto ■ $(8, 8)$

Player \bigcirc can adapt his strategy in function of the choice of Player $\square \rightsquigarrow$ finite-memory strategy!

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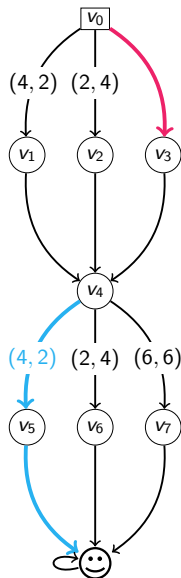
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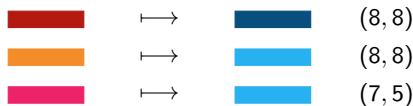


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Player \bigcirc can adapt his strategy in function of the choice of Player $\square \rightsquigarrow$ finite-memory strategy!

$$\text{Ensure}(v) = \{\mathbf{c} \in \overline{\mathbb{N}}^d \mid \exists \sigma_{\circlearrowleft} \text{ st. } \forall \sigma_{\square}, \text{Cost}(\langle \sigma_{\circlearrowleft}, \sigma_{\square} \rangle_v) \leq_{\mathbf{c}} \mathbf{c}\}.$$

$\text{minimal}(\text{Ensure}(v)) = \text{Pareto}(v) \rightsquigarrow$ **Pareto frontier** from v .

For $\mathbf{c} = (c_1, \dots, c_d) \in \text{Pareto}(v)$, a strategy $\sigma_{\circlearrowleft}$ is **c-Pareto-optimal** if $\sigma_{\circlearrowleft}$ ensures \mathbf{c} from v .

Studied problems

- 1 Compute the Pareto frontier and Pareto-optimal strategies.
- 2 Decide the **constrained existence problem**.

Constrained existence problem (CEP)

Given a game, a vertex $v \in V$ and $\mathbf{c} \in \mathbb{N}^d$, does there exist a strategy σ_{\bigcirc} of Player \bigcirc such that for all strategies of Player \square , we have:

$$\text{Cost}(\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_v) \leq_{\mathbf{c}} \mathbf{c}$$

Computing Pareto(v)

$$\text{Ensure}^k(v) = \{c \in \bar{\mathbb{N}}^d \mid \exists \sigma_{\circ} \text{ st. } \forall \sigma_{\square}, \\ \text{Cost}(\langle \sigma_{\circ}, \sigma_{\square} \rangle_v) \leq c \wedge |\langle \sigma_{\circ}, \sigma_{\square} \rangle_v|_F \leq k\}.$$

The algorithm computes, step by step, the sets $I^k(v)$ for all $v \in V$.

For all $k \in \mathbb{N}$ and all $v \in V$, $I^k(v) = \text{minimal}(\text{Ensure}^k(v))$

There exists $k^* \in \mathbb{N}$ such that for all $v \in V$ and for all $\ell \in \mathbb{N}$,
 $I^{k^*}(v) = I^{k^*+\ell}(v)$.

For all $v \in V$, $I^{k^*}(v) = \text{Pareto}(v)$.

Theorem

The fixpoint algorithm runs in time polynomial in W and $|V|$ and is **exponential** in d .

Where W is the maximal weight on an edge.

Computing Pareto(v) and Pareto-optimal strategies

```
for  $v \in F$  do  $l^0(v) = \{0\}$ 
for  $v \notin F$  do  $l^0(v) = \{\infty\}$ 

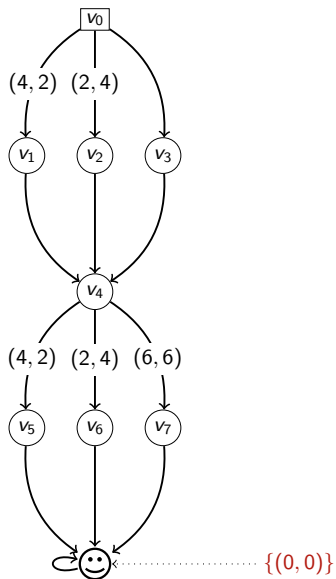
repeat
  for  $v \in V$  do
    if  $v \in F$  then  $l^{k+1}(v) = \{0\}$ 

    else if  $v \in V_{\square}$  then
       $l^{k+1}(v) = \text{minimal} \left( \bigcup_{v' \in \text{succ}(v)} \uparrow l^k(v') + \mathbf{w}(v, v') \right)$ 

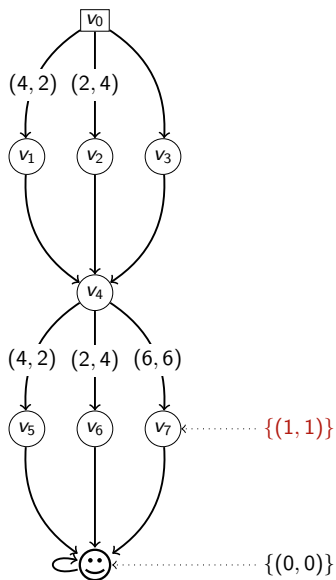
    else if  $v \in V_{\square}$  then
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until  $l^{k+1}(v) = l^k(v)$  for all  $v \in V$ 
```

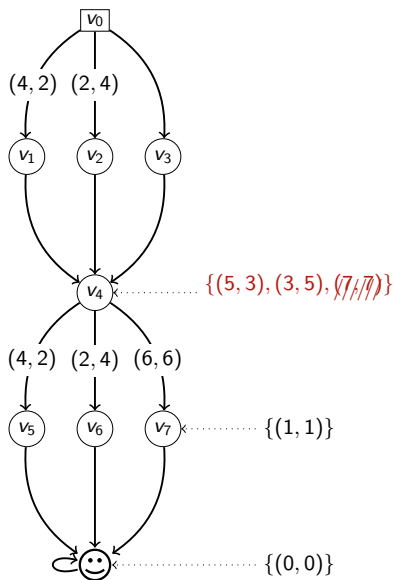
Computing Pareto(v)



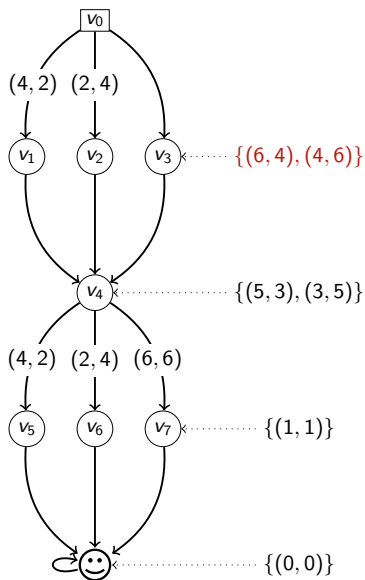
Computing Pareto(v)



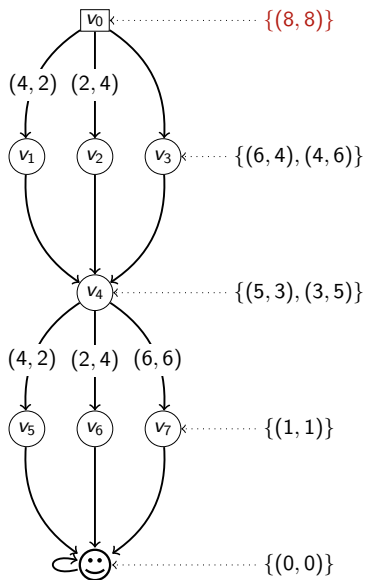
Computing Pareto(v)



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Computing Pareto(v)



Pareto-optimal strategies

```
for  $v \in F$  do  $l^0(v) = \{0\}$   
for  $v \notin F$  do  $l^0(v) = \{\infty\}$ 
```

```
repeat
```

```
  for  $v \in V$  do  
    if  $v \in F$  then  $l^{k+1}(v) = \{0\}$ 
```

```
    else if  $v \in V_{\square}$  then
```

$$l^{k+1}(v) = \text{minimal} \left(\bigcup_{v' \in \text{succ}(v)} \uparrow l^k(v') + \mathbf{w}(v, v') \right)$$

```
      for  $x \in l^{k+1}(v)$  do
```

```
        if  $x \in l^k(v)$  then  $f_v^{k+1}(x) = f_v^k(x)$ 
```

```
        else
```

```
           $f_v^{k+1}(x) = (v', x')$  where  $v'$  and  $x'$  are such that  $v' \in \text{succ}(v)$ ,  $x = x' + \mathbf{w}(v, v')$  and  $x' \in l^k(v')$ 
```

```
    else if  $v \in V_{\square}$  then
```

$$l^{k+1}(v) = \text{minimal} \left(\bigcap_{v' \in \text{succ}(v)} \uparrow l^k(v') + \mathbf{w}(v, v') \right)$$

```
until  $l^{k+1}(v) = l^k(v)$  for all  $v \in V$ 
```


Computing Pareto-optimal strategies

Given $u \in V$ and $\mathbf{c} \in I^*(u) \setminus \{\infty\}$, we define a strategy σ_{\circ}^* from u such that for all $hv \in \text{Hist}_{\circ}(u)$, let $\mathcal{C}(hv) = \{\mathbf{x}' \in I^*(v) \mid \mathbf{x}' \leq_{\mathbf{C}} \mathbf{c} - \text{Cost}(hv) \wedge \mathbf{x}' \leq_{\mathbf{L}} \mathbf{c} - \text{Cost}(hv)\}$,

$$\sigma_{\circ}^*(hv) = \begin{cases} v' & \text{for some } v' \in \text{succ}(v), \text{ if } \mathcal{C}(hv) = \emptyset \\ f_v^*(\mathbf{x})[1] & \text{where } \mathbf{x} = \min_{\leq_{\mathbf{L}}} \mathcal{C}(hv), \text{ if } \mathcal{C}(hv) \neq \emptyset \end{cases}.$$

σ_{\circ}^* is a \mathbf{c} -Pareto-optimal strategy from u .

Conclusion

Conclusion

	Componentwise order	Lexicographic order
$\text{minimal}(\text{Ensure}(v))$	in exponential time	in polynomial time
CEP	PSPACE-complete	in P

- **uniform approach** to compute $\text{minimal}(\text{Ensure}(v))$ both for the componentwise order and the lexicographic order \rightsquigarrow fixpoint algorithm;
- (Pareto)-optimal strategies can be synthesized thanks to the fixpoint algorithm;
- Pareto-optimal strategies may **require memory**.

